

# Tutorenprogramm - Strömungsmechanik I

## Kontinuitäts- und Bernoulligleichung - Musterlösung

### 1. Aufgabe

1. HGG und Bernoulli von  $[0]$  nach  $[k]$ :

$$\text{außen: } p_{a_0} = p_{a_k} + \rho_L g(h_k - h_0) \quad \text{mit} \quad k = 1, 2$$

$$\text{innen: } p_{a_0} = p_{a_k} + \frac{\rho_G}{2} v_{G_k}^2 + \rho_G g(h_k - h_0)$$

$$p_{a_0} + \rho_L g h_0 = p_{a_k} + \frac{\rho_G}{2} v_{G_k}^2 + \rho_G g(h_k - h_0) + \rho_L g h_0$$

$$v_{G_k} = \sqrt{2g(h_k - h_0)\left(\frac{\rho_L}{\rho_G} - 1\right)}$$

$$\text{Konti: } v_{G_2} \frac{\pi d_2^2}{4} = v_{G_1} \frac{\pi d_1^2}{4}$$

$$\frac{v_{G_1}}{v_{G_2}} = \frac{d_2^2}{d_1^2} \quad \Rightarrow \quad \frac{d_1}{d_2} = \sqrt{\frac{v_{G_2}}{v_{G_1}}}$$

$$\frac{d_1}{d_2} = \sqrt[4]{\frac{h_2 - h_0}{h_1 - h_0}}$$

2. Bernoulli von  $[0]$  nach  $[2]$ :

$$\text{außen: } p_{a_0} = p_{a_2} + \rho_L g(h_2 - h_0)$$

$$\text{innen: } p_{a_0} = p_{a_2} + (1 + \zeta_{Dr}) \frac{\rho_G}{2} v_{G_2}^2 + \rho_G g(h_2 - h_0)$$

$$d_1 = d_2 \quad , \quad \dot{V}_1 = \dot{V}_2 \quad \Rightarrow \quad v_{G_2} = v_{G_1}$$

$$\zeta_{Dr} = \frac{h_2 - h_1}{h_1 - h_0}$$

Quelle: Herbst 2010

## 2. Aufgabe

1.

$$F = (p_a + \varrho_1 g H_1 - p_a - \varrho_2 g H_2) \frac{\pi d^2}{4} = \frac{\pi d^2 g}{4} (\varrho_1 H_1 - \varrho_2 H_2)$$

2. Druck in 2 ist gleich:

$$p_a + \varrho_1 g h_1 = p_a + \varrho_2 g h_a + \varrho_1 g h_b$$

$$h_a + h_b = h_2 \text{ gleiches Volumen : } \varrho_1 A H_1 = \varrho_1 A h_1 + \varrho_1 A h_b$$

$$\Rightarrow h_b = H_1 - h_1 \quad \varrho_2 A H_2 = \varrho_2 A h_a \Rightarrow h_a = H_2$$

$$\Rightarrow \varrho_1 g h_1 = \varrho_2 g H_2 + \varrho_1 g (H_1 - h_1) \Rightarrow h_1 = \frac{\varrho_2 H_2 + \varrho_1 H_1}{2 \varrho_1}$$

$$h_2 = H_2 + H_1 - h_1$$

3. Bernoulli:  $3 \rightarrow 4$

$$p_3 + \frac{\varrho_2}{2} v_3^2 = p_a + \frac{\varrho_2}{2} v_4^2 + \varrho_2 g h_a$$

Konti:

$$v_3 = v_4 = v_1 \quad h_a = H_2 \quad v_2 = v_1 \frac{4A}{\pi d^2} \quad v_1 = \frac{-dh_1}{dt}$$

Bernoulli:  $1 \rightarrow 3$

$$\begin{aligned} p_a + \frac{\varrho_1}{2} v_1^2 + \varrho_1 g h_1 &= p_3 + \frac{\varrho_1}{2} v_3^2 + \varrho_1 g h_b + \varrho_1 L \frac{dv_2}{dt} \\ \Rightarrow \varrho_1 g h_1 + \varrho_1 L \frac{4A}{\pi d^2} \frac{d^2 h_1}{dt^2} &= \varrho_2 g H_2 + \varrho_1 g h_b \end{aligned}$$

mit  $h_b = H_1 - h_1$

$$\Rightarrow \underbrace{\varrho_1 L \frac{4A}{\pi d^2} \frac{d^2 h_1}{dt^2}}_a + \underbrace{2\varrho_1 g h_1}_b - \underbrace{(\varrho_2 g H_2 + \varrho_1 g H_1)}_{c<0} = 0$$

DGL:

$$a \cdot \ddot{h}_1 + b \cdot h_1 + c = 0$$

4. Hinweis:

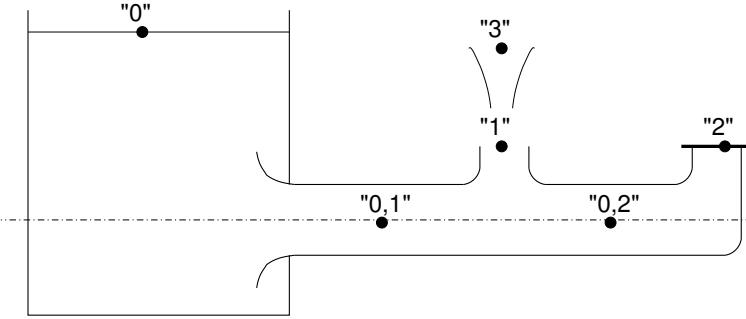
$$h(t) = \frac{-c}{b} + C_1 \sin \sqrt{\frac{b}{a}} t + C_2 \cos \sqrt{\frac{b}{a}} t$$

R.B.:

$$\begin{aligned} h_1(t=0) = H_1 \quad \sin 0 = 0 \quad \cos 0 = 1 &\Rightarrow C_2 = H_1 + \frac{c}{b} \\ v_1(t=0) = 0 \quad \Rightarrow C_1 = 0 \end{aligned}$$

Quelle: Frühjahr 2011

### 3. Aufgabe



$$1. \text{ Bernoulli } 0 \rightarrow 1: p_a + \varrho g H = p_a + \varrho g H_1 + \frac{\varrho}{2} v_1^2 + \frac{\varrho}{2} v_{0,1}^2 \lambda \frac{L_1}{D}$$

$$\text{Konti: } v_{0,1} = \frac{v_1}{4}$$

$$\rightarrow v_1 = \sqrt{\frac{2g(H - H_1)}{1 + \frac{\lambda}{16} \frac{L_1}{D}}}$$

$$\text{Bernoulli } 1 \rightarrow 3: \frac{\varrho}{2} v_1^2 = \varrho g h_1 \rightarrow h_1 = \frac{H - H_1}{1 + \frac{\lambda}{16} \frac{L_1}{D}}$$

$$2. \text{ siehe a): Bernoulli } 0 \rightarrow 1: p_a + \varrho g H = p_a + \varrho g H_1 + \frac{\varrho}{2} \bar{v}_{0,1}^2 \lambda \frac{L_1}{D} + \frac{\varrho}{2} v_{1,b}^2 \quad (*)$$

$$\text{Bernoulli } 0 \rightarrow 2: p_a + \varrho g H = p_a + \varrho g H_1 + \frac{\varrho}{2} \bar{v}_{0,1}^2 \lambda \frac{L_1}{D} + \frac{\varrho}{2} v_2^2 + \frac{\varrho}{2} v_{0,2}^2 \lambda \frac{L_2}{D} \quad (**)$$

$$\text{Mit Konti: } v_{0,2} = \frac{v_2}{4}$$

$$(*) - (**): v_2 = v_{1,b} \sqrt{\frac{1}{1 + \frac{\lambda}{16} \frac{L_2}{D}}}$$

$$\text{Konti: } \bar{v}_{0,1} = \frac{v_{1,b} + v_2}{4}$$

$$\text{In } (*): \varrho g (H - H_1) = \frac{\varrho}{2} v_{1,b}^2 \left( 1 + \frac{\lambda}{16} \frac{L_1}{D} \left( 1 + \sqrt{\frac{1}{1 + \frac{\lambda}{16} \frac{L_2}{D}}} \right)^2 \right)$$

$$\rightarrow v_{1,b} = \sqrt{2g(H - H_1) / \left( 1 + \frac{\lambda}{16} \frac{L_1}{D} \left( 1 + \sqrt{\frac{1}{1 + \frac{\lambda}{16} \frac{L_2}{D}}} \right)^2 \right)}$$

$$3. \text{ instat. Bernoulli } 0 \rightarrow 2: p_a + \varrho g H = p_a + \varrho g H_1 + \frac{\varrho}{2} v_2^2 + \frac{\varrho}{2} v_{0,1}^2 \lambda \frac{L_1}{D} + \frac{\varrho}{2} v_{0,2}^2 \lambda \frac{L_2}{D} + \varrho \int_0^2 \frac{\partial v}{\partial t} ds$$

$$\rightarrow p_a + \varrho g H = p_a + \varrho g H_1 + \frac{\varrho}{2} v_2^2 + \frac{\varrho}{2} v_{0,1}^2 \lambda \frac{L_1}{D} + \frac{\varrho}{2} v_{0,2}^2 \lambda \frac{L_2}{D} + \varrho L_1 \frac{dv_{0,1}}{dt} + \varrho L_2 \frac{dv_{0,2}}{dt}$$

$$\text{instat. Bernoulli } 0 \rightarrow 1: p_a + \varrho g H = p_a + \varrho g H_1 + \frac{\varrho}{2} v_1^2 + \frac{\varrho}{2} v_{0,1}^2 \lambda \frac{L_1}{D} + \varrho L_1 \frac{dv_{0,1}}{dt}$$

$$\text{DGL: } \frac{dv_2}{dt} + \underbrace{\frac{2}{L_2} (1 + \lambda \frac{L_2}{16D}) v_2^2}_{=k_2} - \underbrace{\frac{2}{L_2} v_1^2}_{=k_1} = 0$$

Quelle: Herbst 2009

#### 4. Aufgabe

a) Kontinuitätsgleichung:

$$\begin{aligned}\dot{V} &= v_3 \cdot \frac{\pi d^2}{4} = v_1 \cdot \frac{\pi D^2}{4} \\ \Rightarrow v_3 &= \frac{4\dot{V}}{\pi d^2}, \quad v_1 = \frac{4\dot{V}}{\pi D^2}\end{aligned}$$

Bernoulli  $\boxed{0} \rightarrow \boxed{3}$  :

$$\begin{aligned}p_i + \rho g H &= p_a + \rho gh + \frac{\rho}{2} v_3^2 \left( 1 + \lambda \frac{L}{d} \right) + \frac{\rho}{2} v_1^2 \left( \zeta_S + \zeta_V + \lambda \frac{2L}{D} \right) \\ \Rightarrow p_i + \rho g H &= p_a + \rho gh + \frac{\rho}{2} v_3^2 \left( 1 + \lambda \frac{L}{d} + \left[ \frac{d}{D} \right]^4 \cdot \left[ \zeta_S + \zeta_V + \lambda \frac{2L}{D} \right] \right) \\ \Leftrightarrow p_i &= p_a - \rho g (H - h) + \frac{\rho}{2} v_3^2 \left( 1 + \lambda \frac{L}{d} + \left[ \frac{d}{D} \right]^4 \cdot \left[ \zeta_S + \zeta_V + \lambda \frac{2L}{D} \right] \right) \\ \Leftrightarrow p_i &= p_a - \rho g (H - h) + \frac{\rho}{2} \left( \frac{16\dot{V}^2}{\pi^2 d^4} \right) \cdot \left( 1 + \lambda \frac{L}{d} + \left[ \frac{d}{D} \right]^4 \cdot \left[ \zeta_S + \zeta_V + \lambda \frac{2L}{D} \right] \right) \quad \left[ \frac{N}{m^2} \right]\end{aligned}$$

b) Torricelli:

$$v_{4,end} = \sqrt{2 \frac{p_i - p_a}{\rho} + 2g(H + L)}$$

instationärer Bernoulli  $\boxed{0} \rightarrow \boxed{4}$  :

$$p_i + \rho g (H + L) = p_a + \frac{\rho}{2} v_4^2 + \rho \int_0^{2L} \frac{\partial v_1}{\partial t} ds + \rho \int_0^L \frac{\partial v_4}{\partial t} ds$$

$$\text{Mit Hinweis } L \gg D: \int_0^{2L} \frac{\partial v_1}{\partial t} ds = \int_0^{2L} \frac{dv_1}{dt} ds \quad \& \quad \int_0^L \frac{\partial v_4}{\partial t} ds = \int_0^{4L} \frac{dv_4}{dt} ds$$

Kontinuitätsgleichung:

$$\begin{aligned}v_1 \frac{\pi D^2}{4} &= v_4 \frac{\pi d^2}{4} \Rightarrow v_1 = v_4 \frac{d^2}{D^2} \quad ; \quad \frac{dv_1}{dt} = \frac{dv_4}{dt} \frac{d^2}{D^2} \\ \Rightarrow p_i + \rho g (H + L) &= p_a + \frac{\rho}{2} v_4^2 + \rho \int_0^{2L} \frac{dv_4}{dt} \frac{d^2}{D^2} ds + \rho \int_0^L \frac{dv_4}{dt} ds \\ \Rightarrow p_i + \rho g (H + L) &= p_a + \frac{\rho}{2} v_4^2 + \rho \frac{dv_4}{dt} L \left( 2 \frac{d^2}{D^2} + 1 \right) \\ \frac{2 \frac{p_i - p_a}{\rho} + 2g(H + L) - v_4^2}{2L \left( 2 \frac{d^2}{D^2} + 1 \right)} &= \frac{dv_4}{dt} \\ dt &= \frac{2L \left( 2 \frac{d^2}{D^2} + 1 \right) dv_4}{2 \frac{p_i - p_a}{\rho} + 2g(H + L) - v_4^2}\end{aligned}$$

$$\text{Mit Hinweis: } a^2 = 2 \frac{p_i - p_a}{\rho} + 2g(H + L)$$

$a > |v_4|$ , da  $v_{4,end} = a$

$$\Rightarrow \Delta T = \frac{2L \left( 2 \frac{d^2}{D^2} + 1 \right)}{2 \sqrt{2 \frac{p_i - p_a}{\rho} + 2g(H + L)}} \ln \left( \frac{v_{4,end} + v_4}{v_{4,end} - v_4} \right)$$

Einsetzen der Bedingung  $v_4 = 0,9 \cdot v_{4,end}$ :

$$\Rightarrow \Delta T = \frac{2L \left( 2 \frac{d^2}{D^2} + 1 \right)}{2\sqrt{2 \frac{p_i - p_a}{\rho} + 2g(H+L)}} \ln(19)$$
$$\left[ \frac{m}{\sqrt{\frac{k g m^4}{m^2 s^2 k g} + \frac{m^2}{s^2}}} \right] = [s]$$

Quelle: Herbst 2013